## Conditional probability and independence

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## Probability and Statistics <br> BIE-PST, WS 2023/24, Lecture 2



## Content

- Probability theory:
- Events, probability, conditional probability, Bayes' Theorem, independence of events.
- Random variables, distribution function, functions of random variables, characteristics of random variables: expected value, variance, moments, generating function, quantiles, critical values, covariance and correlation, important discrete and continuous distributions.
- Random vectors, joint and marginal distributions, functions of random vectors, independence of random variables, conditional distribution, conditional expected value.
- Markov's and Chebyshev's inequality, weak law of large numbers, strong law of large numbers, Central limit theorem.
- Mathematical statistics:
- Point estimators, sample mean, sample variance, properties of point estimators, Maximum likelihood method.
- Interval estimators, hypothesis testing, one-sided vs. two-sided alternatives, linear regression, estimators of regression parameters, testing of linear model.


## Recap

A random experiment is represented using a probability space $(\Omega, \mathcal{F}, \mathrm{P})$ :

- $\Omega$ is the set of possible results;
- $\mathcal{F}$ is a system of subsets of $\Omega$;
- elements $A \in \mathcal{F}$ are called random events;
- the probability measure P is a function, which assigns to the random events a real value from 0 to 1 , representing the ideal proportion of cases, in which the events occur.

If there is only a finite many possible results with equal probabilities, then

$$
\mathrm{P}(A)=\frac{|A|}{|\Omega|}
$$

## Conditional probability

How does the probability change if we have partial information about the result of the experiment?

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If we know that an even number was rolled, then it is clear that $\mathrm{P}(4 \mid$ even $)=1 / 3$.

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If we know that an event $B$ surely occurred, we are in fact interested only in outcomes of the experiment favorable to the event $B$. Favorable outcomes to the event $A$ are now in $A \cap B$ and all of them must be in $B$ ( $B$ surely occurred). We have

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\mathrm{P}(A \mid B)=\frac{\operatorname{size}(A \cap B)}{\operatorname{size}(B)}=\frac{\operatorname{size}(A \cap B) / \operatorname{size}(\Omega)}{\operatorname{size}(B) / \operatorname{size}(\Omega)}=\frac{\mathrm{P}(A \cap B)}{\mathrm{P}(B)}
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## Definition

Let $A, B$ be events and $\mathrm{P}(B)>0$. The conditional probability of the event $A$ given (the event) $B$ is denoted by $\mathrm{P}(A \mid B)$ and is defined as

$$
\mathrm{P}(A \mid B)=\frac{\mathrm{P}(A \cap B)}{\mathrm{P}(B)} .
$$

## Conditional probability - Venn diagram



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\mathrm{P}(\text { intersection })=\mathrm{P}(\text { event } \mid \text { condition }) \mathrm{P}(\text { condition })
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## Conditional probability - examples

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Consider two rolls of a die. What is $\mathrm{P}($ sum $>6 \mid$ first $=3)$ ?

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The answer is surely $1 / 2$, since the second rolled number must be 4,5 , or 6 .
Formally: $\Omega=\{1,2,3,4,5,6\}^{2}$,
$\mathrm{P}(A)=|A| / 36$ for each $A \subset \Omega$.
Let $B=\left\{\left(3, \omega_{2}\right): 1 \leq \omega_{2} \leq 6\right\}, \quad A=\left\{\left(\omega_{1}, \omega_{2}\right): \omega_{1}+\omega_{2}>6\right\}$.

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Then

$$
\mathrm{P}(A \mid B)=\frac{\mathrm{P}(A \cap B)}{\mathrm{P}(B)}=\frac{\frac{|A \cap B|}{36}}{\frac{|B|}{36}}=\frac{|A \cap B|}{|B|}=\frac{3}{6}
$$

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## Example - family with two children

A trickier example:
A family has two children. What is the probability that both are boys, given that at least one of them is a boy? I.e., what is the value of P (both boys | at least one is a boy)?

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\mathrm{P}(B B \mid B G \cup G B \cup B B) & =\frac{\mathrm{P}(B B \cap(B G \cup G B \cup B B))}{\mathrm{P}(B G \cup B G \cup B B)} \\
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Incorrect: $\mathrm{P}(B B \mid$ older is boy $)=\mathrm{P}(B B \mid B G \cup B B)=\frac{\mathrm{P}(B B \cap(B G \cup B B))}{\mathrm{P}(B G \cup B B)}=\frac{1}{2}$.

## Properties of conditional probability

## Lemma

Let $\mathrm{P}(B)>0$. Then the conditional probability $\mathrm{P}(\cdot \mid B)$ is a probability measure, i.e., $\mathrm{P}(\cdot \mid B) \in[0,1]$ and it fulfills the axioms of probability.

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iv) $\sigma$-additivity: If $A_{1}, A_{2}, \ldots \in \mathcal{F}$ are mutually disjoint events (i.e., $A_{i} \cap A_{j}=\emptyset$ for $\forall i, j: i \neq j$ ), then

$$
\mathrm{P}\left(\bigcup_{i=1}^{+\infty} A_{i} \mid B\right)=\frac{\mathrm{P}\left(\left(\bigcup_{i=1}^{+\infty} A_{i}\right) \cap B\right)}{\mathrm{P}(B)}=\frac{\mathrm{P}\left(\bigcup_{i=1}^{+\infty}\left(A_{i} \cap B\right)\right)}{\mathrm{P}(B)}=\cdots=\sum_{i=1}^{+\infty} \mathrm{P}\left(A_{i} \mid B\right) .
$$

## Properties of conditional probability

Conditional probability fulfills all mentioned properties of probability as well:

- if $A_{1}$ and $A_{2}$ are mutually disjoint, then $\mathrm{P}\left(A_{1} \cup A_{2} \mid B\right)=\mathrm{P}\left(A_{1} \mid B\right)+\mathrm{P}\left(A_{2} \mid B\right)$,
- $\mathrm{P}\left(A_{1} \cup A_{2} \mid B\right)=\mathrm{P}\left(A_{1} \mid B\right)+\mathrm{P}\left(A_{2} \mid B\right)-\mathrm{P}\left(A_{1} \cap A_{2} \mid B\right)$,
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- etc.


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Moreover, the probability $\mathrm{P}(A \mid B)$ "lives" on $B$ : for $A \cap B=\emptyset$ we have $\mathrm{P}(A \mid B)=0$.
Furthermore, $\mathrm{P}(A \cap B \mid B)=\frac{\mathrm{P}(A \cap B \cap B)}{\mathrm{P}(B)}=\frac{\mathrm{P}(A \cap B)}{\mathrm{P}(B)}=\mathrm{P}(A \mid B)$.

## Case distinct formula (Law of total probability)

$\Omega=B_{1} \cup B_{2} \cup B_{3}$ (disjoint partition)

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Recall:

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\mathrm{P}\left(A \mid B_{i}\right)=\frac{\mathrm{P}\left(A \cap B_{i}\right)}{\mathrm{P}\left(B_{i}\right)}
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## Bayes' Theorem (Thomas Bayes, 1701-1761)

A family of mutual disjoint events $B_{1}, B_{2}, \ldots B_{n}$ is called a partition of the set $\Omega$, if

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Theorem - case distinct formula (Law of total probability)
Let $B_{1}, B_{2}, \ldots, B_{n}$ be a partition of $\Omega$ such that $\forall i: \mathrm{P}\left(B_{i}\right)>0$.
Then for each event $A$ it holds that

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## Theorem - Bayes' Theorem

Let $B_{1}, B_{2}, \ldots, B_{n}$ be a partition of $\Omega$ such that $\forall i: \mathrm{P}\left(B_{i}\right)>0$ and let $A$ be an event with $\mathrm{P}(A)>0$. Then it holds that

$$
\mathrm{P}\left(B_{j} \mid A\right)=\frac{\mathrm{P}\left(A \mid B_{j}\right) \mathrm{P}\left(B_{j}\right)}{\sum_{i=1}^{n} \mathrm{P}\left(A \mid B_{i}\right) \mathrm{P}\left(B_{i}\right)} .
$$

## Bayes' Theorem - example

## Example - spam filter

From the analysis of our email account we find out that:

- $30 \%$ of all delivered messages is spam;
- in $70 \%$ of spam messages there is the word "copy";
- only in $10 \%$ of non-spam messages there is the word "copy".

Calculate the probability that a message containing the word "copy" is a spam,

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Calculate the probability that a message containing the word "copy" is a spam,
$S$ : set of spam messages,
$S^{c}=\Omega \backslash S$ : set of non-spam messages,
$C$ : set of messages containing word "copy",
$C^{c}$ : set of messages not containing the word "copy".

$$
\mathrm{P}(S)=0.3, \mathrm{P}\left(S^{c}\right)=0.7, \quad \mathrm{P}(C \mid S)=0.7, \mathrm{P}\left(C \mid S^{c}\right)=0.1
$$

## Bayes' Theorem - example

## Example - spam filter

From the analysis of our email account we find out that:

- $30 \%$ of all delivered messages is spam;
- in $70 \%$ of spam messages there is the word "copy";
- only in $10 \%$ of non-spam messages there is the word "copy".

Calculate the probability that a message containing the word "copy" is a spam,
$S$ : set of spam messages,
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\mathrm{P}(S)=0.3, \mathrm{P}\left(S^{c}\right)=0.7, \quad \mathrm{P}(C \mid S)=0.7, \mathrm{P}\left(C \mid S^{c}\right)=0.1 \\
\mathrm{P}(S \mid C)=\frac{\mathrm{P}(C \mid S) \mathrm{P}(S)}{\mathrm{P}(C \mid S) \mathrm{P}(S)+\mathrm{P}\left(C \mid S^{c}\right) \mathrm{P}\left(S^{c}\right)}=\frac{0.7 \cdot 0.3}{0.7 \cdot 0.3+0.1 \cdot 0.7}=\frac{21}{28}=0.75
\end{gathered}
$$

## Probability trees

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First let us recall a useful relation:
From the definition of conditional probability it follows that:

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\mathrm{P}(A \cap B)=\mathrm{P}(A \mid B) \mathrm{P}(B)
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which can be proven by using the definition of conditional probability on the right hand side:

$$
\begin{aligned}
\mathrm{P}(A) \mathrm{P}(B \mid A) \mathrm{P}(C \mid A \cap B) & =\mathrm{P}(A) \frac{\mathrm{P}(B \cap A)}{\mathrm{P}(A)} \frac{\mathrm{P}(C \cap(A \cap B))}{\mathrm{P}(A \cap B)} \\
& =\mathrm{P}(A \cap B \cap C)
\end{aligned}
$$

## Probability trees

## Lemma - Multiplicative law

Let for events $A_{1}, \ldots, A_{n}$ hold that $\mathrm{P}\left(A_{1} \cap \cdots \cap A_{n}\right)>0$. Then it holds that
$\mathrm{P}\left(A_{1} \cap \cdots \cap A_{n}\right)=\mathrm{P}\left(A_{1}\right) \mathrm{P}\left(A_{2} \mid A_{1}\right) \mathrm{P}\left(A_{3} \mid A_{1} \cap A_{2}\right) \ldots \mathrm{P}\left(A_{n} \mid A_{1} \cap \cdots \cap A_{n-1}\right)$.

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$$

## Proof

We apply successively the relation $\mathrm{P}(A \cap B)=\mathrm{P}(A) \mathrm{P}(B \mid A)$ following from the definition of conditional probability:

$$
\begin{aligned}
\mathrm{P}\left(A_{1} \cap \cdots \cap A_{n}\right) & =\mathrm{P}\left(A_{1} \cap \cdots \cap A_{n-1}\right) \mathrm{P}\left(A_{n} \mid A_{1} \cap \cdots \cap A_{n-1}\right) \\
& =\mathrm{P}\left(A_{1} \cap \cdots \cap A_{n-2}\right) \mathrm{P}\left(A_{n-1} \mid A_{1} \cap \cdots \cap A_{n-2}\right) \mathrm{P}\left(A_{n} \mid A_{1} \cap \cdots \cap A_{n-1}\right) \\
& =\ldots
\end{aligned}
$$

## Example - spam filter



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$$
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$$
\mathrm{P}(S \mid C)=\frac{\mathrm{P}(S \cap C)}{\mathrm{P}(C)}=\frac{0.21}{0.21+0.07}=0.75
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The probability of a given vertex of the tree is the product of the corresponding values on the path stemming from the root.

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- This means that $90 \%$ of fatal accidents are caused by sober drivers!


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- This means that $90 \%$ of fatal accidents are caused by sober drivers!
- Does this mean that we should should beware of the sober drivers?


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Example - driving under influence continued
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Of course not. We have to carefully read the probabilities.

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The figure tells us that among all accidents, the percentage caused by drunk drivers is $10 \%$. Thus

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\mathrm{P}(\text { drunk } \mid \text { accident })=0.1
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$$
\begin{aligned}
\frac{\mathrm{P}(\text { accident } \mid \text { drunk })}{\mathrm{P}(\text { accident } \mid \text { sober })} & =\frac{\mathrm{P}(\text { accident } \cap \text { drunk }) / \mathrm{P}(\text { drunk })}{\mathrm{P}(\text { accident } \cap \text { sober }) / \mathrm{P}(\text { sober })} \\
& =\frac{\mathrm{P}(\text { drunk } \mid \text { accident }) \cdot \mathrm{P}(\text { accident }) / \mathrm{P}(\text { drunk })}{\mathrm{P}(\text { sober } \mid \text { accident }) \cdot \mathrm{P}(\text { accident }) / \mathrm{P}(\text { sober })}=\frac{0.1 / 0.01}{0.9 / 0.99}=11
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\end{aligned}
$$

Drunk drivers have at least 11 times higher probability of causing a fatal accident.

## Independence of events

Intuitively: $A$ and $B$ are independent if the probability of the event $A$ is not influenced by the knowledge about occurrence of the event $B$, i.e., $\mathrm{P}(A \mid B)=\mathrm{P}(A)$, and (vice versa) $\mathrm{P}(B \mid A)=\mathrm{P}(B)$.

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$$

Generally, a family of events $\left\{A_{i} \mid i \in I\right\}$ is called independent if

$$
\mathrm{P}\left(\bigcap_{i \in J} A_{i}\right)=\prod_{i \in J} \mathrm{P}\left(A_{i}\right)
$$

for all finite non-empty subsets $J$ of $I$.

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Example - rolling a die
Consider the events
$A$ : "an even number is rolled" and $B$ : "a number less than 3 is rolled".
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\mathrm{P}(A \cap B)=\frac{1}{6} \quad \text { and } \quad \mathrm{P}(A) \mathrm{P}(B)=\frac{3}{6} \cdot \frac{1}{6}=\frac{1}{12} .
\end{gathered}
$$

Then events $A$ and $B$ are not independent.

## Relation between independence and conditional probability

Let $A$ and $B$ be independent events and $\mathrm{P}(B)>0$. Then clearly

$$
\mathrm{P}(A \mid B)=\frac{\mathrm{P}(A \cap B)}{\mathrm{P}(B)}=\frac{\mathrm{P}(A) \mathrm{P}(B)}{\mathrm{P}(B)}=\mathrm{P}(A) .
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For $A$ and $B$ independent the knowledge of $B$ does not bring us any information about $A$.

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## Theorem

If the events $A$ and $B$ are independent then $A$ and $B^{c}$ (resp., $A^{c}$ and $B ; A^{c}$ and $B^{c}$ ) are independent, too.

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## Theorem

If $\left(A_{i}\right)_{i \in I}$ is a family of independent events, then for any arbitrary non-empty finite subset $\emptyset \neq J \subset I$ it holds that

$$
\mathrm{P}\left(\bigcap_{i \in J} A_{i} \mid \bigcap_{i \in I \backslash J} A_{i}\right)=\mathrm{P}\left(\bigcap_{i \in J} A_{i}\right) .
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If $A$ and $B$ are disjoint with non-zero probabilities, then the knowledge that $B$ occurred tells us that $A$ cannot occur.

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If $A$ and $B$ are disjoint with non-zero probabilities, then the knowledge that $B$ occurred tells us that $A$ cannot occur.

The events being disjoint is a matter of sets, independence is a matter of probabilities.

## Conditional independence

## Definition

Let $(\Omega, \mathcal{F}, \mathrm{P})$ be a probability space and $C$ an event with $\mathrm{P}(C)>0$. Events $A$ and $B$ are called conditionally independent with respect to $C$, if

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## Recall:

- $Q(A)=\mathrm{P}(A \mid C)$ is a probability measure;
- the conditional independence is thus the independence with respect to probability $Q$.


## Conditional independence

## Example - rolling a seven-sided die

Suppose we roll a seven-sided die with all sides equally likely. Consider the events:
$A$ : "an even number is rolled", $B$ : "a number less than 3 is rolled".
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$$
\mathrm{P}(A \cap B)=\frac{1}{7} \quad \text { and } \quad \mathrm{P}(A) \cdot \mathrm{P}(B)=\frac{3}{7} \cdot \frac{2}{7}=\frac{6}{49}
$$

Events $A$ and $B$ are not independent.

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Example - rolling a seven-sided die + condition
Consider further event $C$ : "we rolled at most 6 "

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C=\{1,2,3,4,5,6\}
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\begin{gathered}
\mathrm{P}(A \cap B \mid C)=\frac{\mathrm{P}(A \cap B \cap C)}{\mathrm{P}(C)}=\frac{\mathrm{P}(\{2\})}{\mathrm{P}(\{1, \ldots, 6\})}=\frac{1 / 7}{6 / 7}=\frac{1}{6} \\
\mathrm{P}(A \mid C) \cdot \mathrm{P}(B \mid C)=\frac{3 / 7}{6 / 7} \cdot \frac{2 / 7}{6 / 7}=\frac{1}{6}
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Events $A$ and $B$ are conditionally independent with respect to $C$.

## Recap

- The conditional probability that an event $A$ occurs if we know that an event $B$ with $\mathrm{P}(B)>0$ occured, is defined as $\mathrm{P}(A \mid B)=\frac{\mathrm{P}(A \cap B)}{\mathrm{P}(B)}$.
- Law of total probability: For $A$ and $B$ with $\mathrm{P}(B)>0$ we have

$$
\mathrm{P}(A)=\mathrm{P}(A \mid B) \mathrm{P}(B)+\mathrm{P}\left(A \mid B^{c}\right) \mathrm{P}\left(B^{c}\right)
$$

- Bayes' Theorem: For $A$ and $B$ with $\mathrm{P}(A)>0$ and $\mathrm{P}(B)>0$ we have

$$
\mathrm{P}(B \mid A)=\frac{\mathrm{P}(A \mid B) \mathrm{P}(B)}{\mathrm{P}(A \mid B) \mathrm{P}(B)+\mathrm{P}\left(A \mid B^{c}\right) \mathrm{P}\left(B^{c}\right)}
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- Events $A$ and $B$ are called independent if

$$
\mathrm{P}(A \cap B)=\mathrm{P}(A) \cdot \mathrm{P}(B)
$$

- For independent events $A$ and $B$ the knowledge that one of them occurred or not does not change the probability of the other one happening:

$$
\mathrm{P}(A \mid B)=\mathrm{P}(A) \quad \text { and } \quad \mathrm{P}(B \mid A)=\mathrm{P}(B)
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