Random variables II.

(Characteristics or random variables)

Lecturer:

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Probability and Statistics

BIE-PST, WS 2023/24, Lecture 4



Lecture 4

Content

Probability theory:

- Events, probability, conditional probability, Bayes' Theorem, independence of events.
- Random variables, distribution function, functions of random variables, characteristics of random variables: expected value, variance, moments, generating function, quantiles, critical values, covariance and correlation, important discrete and continuous distributions.
- Random vectors, joint and marginal distributions, functions of random vectors, independence of random variables, conditional distribution, conditional expected value.
- Markov's and Chebyshev's inequality, weak law of large numbers, strong law of large numbers. Central limit theorem.

Mathematical statistics:

- Point estimators, sample mean, sample variance, properties of point estimators, Maximum likelihood method.
- Interval estimators, hypothesis testing, one-sided vs. two-sided alternatives, linear regression, estimators of regression parameters, testing of linear model.



Recap

A random variable X is a measurable function, which assigns real values to the outcomes of a random experiment.



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- The distribution of X gives the information of the probabilities of its values and is uniquely given by the distribution function:

$$F_X(x) = P(X \le x).$$

- There are two major types of random variables:
 - discrete, taking only countably many possible values;
 - continuous, taking values from an interval.

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- A random variable X is a measurable function, which assigns real values to the outcomes of a random experiment.
- The distribution of X gives the information of the probabilities of its values and is uniquely given by the **distribution function**:

$$F_X(x) = P(X \le x).$$

- There are two major types of random variables:
 - **discrete**, taking only countably many possible values:
 - continuous, taking values from an interval.
- The distribution can be given by:
 - for discrete distributions by the **probabilities** of possible values $P(X = x_k)$.
 - \blacktriangleright for continuous distributions by the **density** f_X for which

$$F_X(x) = \int_{-\infty}^x f(t)dt.$$



Expected value

One of the important characteristics of a random variable is its **expected value**.

Definition

The **expected value** (or **expectation** or **mean value**) of a discrete random variable X with values $x_1, x_2, ...$, resp., of a continuous random variable X with density f_X , is given as

$$\operatorname{E} X = \sum_k x_k \operatorname{P}(X = x_k)$$
 (discrete)

resp., as

$$EX = \int_{-\infty}^{\infty} x f_X(x) dx, \quad \text{(continuous)}$$

if the sum or the integral converges absolutely.

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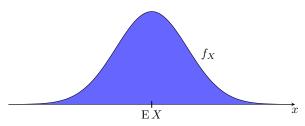
if the sum or the integral converges absolutely.

From the definition it follows that $\operatorname{E} X$ can be interpreted as the x coordinate of the center of the mass of the probability.

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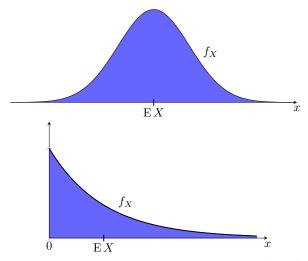
Visualization of the expectation

 $\to X$ is taken as the expected value of the next experiment or as the weighted average (mean) or the center of mass of all possible values.



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Example of the computation of the expectation

Example – tossing two coins

Suppose we throw two balanced coins. Let X denote the number of Heads appearing. Find the expectation of X.

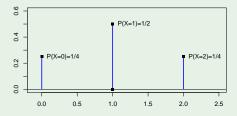
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Suppose we throw two balanced coins. Let X denote the number of Heads appearing. Find the expectation of X.

There are four possible results, which are equally likely: $\Omega=\{TT,HT,TH,HH\}$. Therefore we can obtain 0,1 or 2 Heads, with probabilities of 1/4,1/2 and 1/4, respectively.

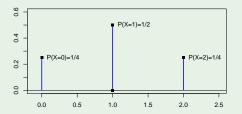


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The expectation is then computed as the probability-weighted average of the possible values:

$$EX = \sum_{k} x_k P(X = x_k) = 0 \cdot \frac{1}{4} + 1 \cdot \frac{1}{2} + 2 \cdot \frac{1}{4} = \frac{1}{2} + \frac{2}{4} = 1.$$

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Example – discrete uniform disribution

Example - rolling a six-sided die

Suppose we roll a balanced six-sided die one time. Let X denote the number of points rolled. What is the expectation of X?

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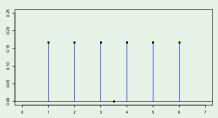
Example – discrete uniform disribution

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The expectation is computed as the weighted average of possible results:

$$EX = \sum_{k=1}^{6} k \cdot P(X = k) = 1 \cdot \frac{1}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{1}{6} + 4 \cdot \frac{1}{6} + 5 \cdot \frac{1}{6} + 6 \cdot \frac{1}{6} = \frac{21}{6} = 3.5.$$



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Example – discrete non-uniform disribution

Example - rolling two six-sided dice

Suppose we roll two balanced six-sided dice and keep the larger result of the two. Let X denote the number of points rolled, meaning $X = \max(\text{roll 1, roll 2})$. What is the expectation of X?

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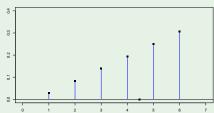
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The expectation is computed as the weighted average of possible results:

$$EX = \sum_{k=1}^{6} k \cdot P(X = k) = \frac{1 \cdot 1 + 2 \cdot 3 + 3 \cdot 5 + 4 \cdot 7 + 5 \cdot 9 + 6 \cdot 11}{36} = \frac{161}{36} \doteq 4.47.$$



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The expected value $\mathrm{E}(g(X))$ of a function of a random variable can be computed without determining the distribution of the random variable Y=g(X).



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Theorem

Let X and Y = g(X) for a given function g be random variables.

i) If X has a discrete distribution, then

$$\operatorname{E} Y = \operatorname{E} g(X) = \sum_{\text{all } x_k} g(x_k) \operatorname{P}(X = x_k),$$

under the assumption that the sum converges absolutely.

ii) If X has a continuous distribution, then

$$\operatorname{E} Y = \operatorname{E} g(X) = \int_{-\infty}^{\infty} g(x) f_X(x) dx,$$

if the integral converges absolutely.

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Proof

Suppose first that X is a discrete random variable. Denote the variable Y=g(X) and its values y_1,y_2,\ldots . Then

$$\begin{split} \mathbf{E}(g(X)) &= \mathbf{E}\,Y = \sum_{\mathbf{all}\,y_j} y_j \,\,\mathbf{P}(Y=y_j) = \sum_{\mathbf{all}\,y_j} y_j \,\,\mathbf{P}(g(X)=y_j) \\ &= \sum_{\mathbf{all}\,y_j} \left(y_j \sum_{x_k:g(x_k)=y_j} \mathbf{P}(X=x_k) \right) = \sum_{\mathbf{all}\,y_j} \sum_{x_k:g(x_k)=y_j} y_j \,\,\mathbf{P}(X=x_k) \\ &= \sum_{\mathbf{all}\,y_j} \sum_{x_k:g(x_k)=y_j} g(x_k) \,\,\mathbf{P}(X=x_k) = \sum_{\mathbf{all}\,x_k} g(x_k) \,\,\mathbf{P}(X=x_k). \end{split}$$

The proof for continuous random variables is more difficult, we achieve it with the help of the following lemma only for function g taking non-negative values.

Lemma

If X is a non-negative random variable with the distribution function F, then

$$\operatorname{E} X = \int_0^\infty [1 - F(x)] \, \mathrm{d}x = \int_0^\infty \operatorname{P}(X > x) \, \mathrm{d}x.$$

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Proof

Suppose that X is a continuous random variable and the function g takes only non-negative values. Then

$$E(g(X)) = EY = \int_0^\infty P(Y > y) dy$$



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Suppose that X is a continuous random variable and the function g takes only non-negative values. Then

$$\mathrm{E}(g(X)) = \mathrm{E}\,Y = \int_0^\infty \mathrm{P}(Y>y)\,\mathrm{d}y = \int_0^\infty \mathrm{P}(g(X)>y)\,\mathrm{d}y$$

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Proof

Suppose that X is a continuous random variable and the function g takes only non-negative values. Then

$$E(g(X)) = EY = \int_0^\infty P(Y > y) dy = \int_0^\infty P(g(X) > y) dy$$
$$= \int_0^\infty \left(\int_{\{x: g(x) > y\}} f_X(x) dx \right) dy$$

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(*) We used
$$P(X \in A) = \int_A f_X(x) dx$$
 for $A = \{x : g(x) > y\}$.



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$$\begin{split} \mathbf{E}(g(X)) &= \mathbf{E} \, Y = \int_0^\infty \mathbf{P}(Y > y) \, \mathrm{d}y = \int_0^\infty \mathbf{P}(g(X) > y) \, \mathrm{d}y \\ &= \int_0^\infty \left(\int_{\{x: \, g(x) > y\}} f_X(x) \, \mathrm{d}x \right) \mathrm{d}y = \iint_{\{(x,y): \, 0 < y < g(x)\}} f_X(x) \, \mathrm{d}(x,y) \\ &= \int_{\{x: \, 0 < g(x)\}} \left(\int_0^{g(x)} f_X(x) \, \mathrm{d}y \right) \, \mathrm{d}x \end{split}$$

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We used $\mathrm{P}(X \in A) = \int_A f_X(x) \, \mathrm{d}x$ for $A = \{x \, ! : g(x) > y\}$. If g is a general function we decompose it to its positive and negative parts which are both non-negative functions. Then we write $\operatorname{E} g(X) = \operatorname{E} Y = \operatorname{E} Y^+ - \operatorname{E} Y^- = \operatorname{E} g^+(X) - \operatorname{E} g^-(X)$ and use the above mentioned proof.

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For computation, the following properties of the expected value are important. Notice that these properties hold for the expectation of both discrete and continuous random variables.

Theorem

The expected value of a random variable X has the following properties:

- i) If $X \ge 0$, then $E(X) \ge 0$.
- ii) If $a, b \in \mathbb{R}$, then E(aX + b) = a E(X) + b (if EX is finite).
- iii) A constant random variable X=c has expectation equal to the constant $\mathrm{E}(X)=c$.

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Notes:

- These properties of expectation do not depend on the type of random variable discrete, continuous or mixed.
- For discrete, continuous or mixed random variables X and Y with finite expectations it holds that (we will prove it later)

$$E(aX + bY) = a EX + b EY, \quad \forall a, b \in \mathbb{R}.$$

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These formulas can be used to simplify practical computing.

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Proof

i) For a discrete non-negative random variable X it holds that $x_k \operatorname{P}(X=x_k) \geq 0, \forall k.$ Therefore $\operatorname{E}(X) = \sum x_k \operatorname{P}(X=x_k) \geq 0.$

For a continuous non-negative random variable X it holds that $f_X(x) = 0$ for x < 0.

Therefore
$$\mathrm{E}(X) = \int_0^\infty x f_X(x) \,\mathrm{d}x \geq 0.$$

ii) For a discrete random variable X it holds that

$$\begin{split} \mathbf{E}(aX+b) &= \sum_{\text{all } x_k} (ax_k+b) \ \mathbf{P}(X=x_k) \\ &= a \sum_{\text{all } x_k} x_k \ \mathbf{P}(X=x_k) + b \sum_{\text{all } x_k} \mathbf{P}(X=x_k) \\ &= a \ \mathbf{E}(X) + b. \end{split}$$

For a continuous random variable X the proof is similar.

iii) Consider a=0 in ii).

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Definition

The variance $\sigma^2 \equiv \operatorname{var} X$ of a random variable X is defined as

$$var X = E(X - EX)^2.$$

The **standard deviation** of a random variable X is defined as

s.d.
$$X = \sqrt{\operatorname{var} X}$$
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The following properties of the variance are useful for practical computations:

Theorem

For the variance it holds that:

i) For all $a,b \in \mathbb{R}$ and a random variable X it holds that

$$var(aX + b) = a^2 var X.$$

ii) A constant random variable $X=c\in\mathbb{R}$ has zero variance (var c=0).

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While computing the variance it is often tedious to calculate the sum of values $(x_i-\operatorname{E} X)^2\operatorname{P}(X=x_i)$ or the integral of $(x-\operatorname{E} X)^2\,f_X(x)$.

We can use properties of the expectation to get a more useful formula:

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$$var(X) = E((X - EX)^{2}) = E(X^{2} - 2X(EX) + (EX)^{2})$$

$$= E(X^{2}) - E(2X(EX)) + E((EX)^{2})$$

$$= E(X^{2}) - 2(EX)(EX) + (EX)^{2}$$

$$= E(X^{2}) - (EX)^{2}.$$

We get the formula: $\operatorname{var}(X) = \operatorname{E}((X - \operatorname{E} X)^2) = \operatorname{E}(X^2) - (\operatorname{E} X)^2$ or simply: $\operatorname{var} X = \operatorname{E}(X - \operatorname{E} X)^2 = \operatorname{E} X^2 - (\operatorname{E} X)^2.$



Variance

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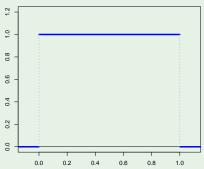
Notice that $\operatorname{var}(X)$ is always non-negative (it is the expectation of a non-negative variable $(X - \operatorname{E} X)^2$). Therefore: $(\operatorname{E} X)^2 \leq \operatorname{E}(X^2)$.

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Example – expectation and variance of the uniform distribution

Suppose that Romeo arrives at the meeting point according to the uniform distribution with the density:

$$f_X(x) = \begin{cases} 1 & \text{for } x \in [0, 1] \\ 0 & \text{otherwise.} \end{cases}$$



What are the expectation and the variance of Romeo's arrival?

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Example – expectation and variance of the uniform distribution

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Example – expectation and variance of the uniform distribution

What are the expectation and the variance of Romeo's arrival?

The expectation can be computed from the definition:

$$EX = \int_{-\infty}^{\infty} x f_X(x) dx = \int_0^1 x 1 dx = \left[\frac{1}{2}x^2\right]_0^1 = \frac{1^2}{2} - \frac{0^2}{2} = \frac{1}{2}.$$

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The expectation of the square is computed similarly:

$$\operatorname{E} X^2 = \int_{-\infty}^{\infty} x^2 f_X(x) dx = \int_0^1 x^2 1 dx = \left[\frac{1}{3} x^3 \right]_0^1 = \frac{1^3}{3} - \frac{0^3}{3} = \frac{1}{3}.$$

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The expectation of the square is computed similarly:

$$EX^{2} = \int_{-\infty}^{\infty} x^{2} f_{X}(x) dx = \int_{0}^{1} x^{2} 1 dx = \left[\frac{1}{3} x^{3} \right]_{0}^{1} = \frac{1^{3}}{3} - \frac{0^{3}}{3} = \frac{1}{3}.$$

The variance is obtained using the computational formula:

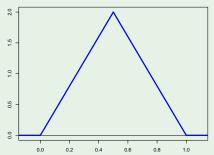
$$\operatorname{var} X = \operatorname{E} X^2 - (\operatorname{E} X)^2 = 1/3 - (1/2)^2 = 4/12 - 3/12 = 1/12.$$

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Example – expectation and variance of a non-uniform distribution

Suppose that Juliet arrives at the meeting point according to a non-uniform distribution with the density:

$$f_Y(y) = \begin{cases} 4y & \text{for } y \in [0, 1/2] \\ 4 - 4y & \text{for } y \in [1/2, 1] \\ 0 & \text{otherwise.} \end{cases}$$



What are the expectation and the variance of Juliet's arrival?

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Example – expectation and variance of a non-uniform distribution

What is the expectation and variance of Juliet's arrival?



Example – expectation and variance of a non-uniform distribution

What is the expectation and variance of Juliet's arrival?

The expectation can be computed from the definition:

$$EY = \int_{-\infty}^{\infty} y f_Y(y) dy = \int_{0}^{1/2} y(4y) dy + \int_{1/2}^{1} y(4-4y) dy = \dots = \frac{1}{2}.$$



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Example – expectation and variance of a non-uniform distribution

What is the expectation and variance of Juliet's arrival?

The expectation can be computed from the definition:

$$EY = \int_{-\infty}^{\infty} y f_Y(y) dy = \int_{0}^{1/2} y(4y) dy + \int_{1/2}^{1} y(4-4y) dy = \dots = \frac{1}{2}.$$

The expectation of the square is computed similarly:

$$EY^2 = \int_{-\infty}^{\infty} y^2 f_Y(y) dy = \int_{0}^{1/2} y^2 (4y) dy + \int_{1/2}^{1} y^2 (4 - 4y) dx = \dots = \frac{7}{24}.$$

The variance is obtained using the computational formula:

$$var Y = EY^{2} - (EY)^{2} = 7/24 - (1/2)^{2} = 7/24 - 6/24 = 1/24.$$

The expectation is the same in both cases, but Romeo's arrivals have a twice larger variance than Juliet's.

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Moments of random variables

Definition

For $k \in \mathbb{N}$ we define the k-th moment μ_k of a random variable X as

$$\mu_k = \mathrm{E}(X^k) = \begin{cases} \sum_{\text{all } x_i} x_i^k \; \mathrm{P}(X = x_i) & \text{discrete} \\ \int_{-\infty}^{\infty} x^k \, f_X(x) \, \mathrm{d}x & \text{continuous.} \end{cases}$$



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Similarly, the k-th central moment σ_k is defined as

$$\sigma_k = \mathrm{E}((X-\mu_1)^k) = \begin{cases} \sum_{\substack{\text{all } x_i \\ -\infty}} (x_i - \mu_1)^k \ \mathrm{P}(X=x_i) & \text{discrete} \\ \int_{-\infty}^{\infty} (x-\mu_1)^k \ f_X(x) \, \mathrm{d}x & \text{continuous.} \end{cases}$$

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<u>Notation:</u> usually we write $E[X^k]$ instead of $E[X^k]$ and $E[X-\mu_1]^k$ instead of $E[(X-\mu_1)^k]$.

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• Moments of a given random variable X do not always exist (if the corresponding sum or integral does not converge).



Lecture 4

- ullet Moments of a given random variable X do not always exist (if the corresponding sum or integral does not converge).
- $\mu_1 = EX$ is the expected value of the variable X (often denoted as μ or μ_X).

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- $\mu_1 = \operatorname{E} X$ is the expected value of the variable X (often denoted as μ or μ_X).
- $\sigma_2 = \mathrm{E}(X \mathrm{E}X)^2$ is the variance of the variable X denoted by $\mathrm{var}(X)$, $\mathrm{var}X$, σ^2 or σ_X^2 .



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- $\mu_1 = \operatorname{E} X$ is the expected value of the variable X (often denoted as μ or μ_X).
- $\sigma_2 = E(X EX)^2$ is the variance of the variable X denoted by var(X), var(X), σ^2 or $\sigma_{\rm v}^2$.
- $\sigma = \sqrt{\operatorname{var}(X)}$ is the standard deviation of the variable X (possible notation σ_X).

Remark

Note that the variance is quadratic and therefore is measured in the units of X squared. The standard deviation is the square root of the variance and is therefore measured in the same units as X. This will be useful later.

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Skewness

The measure of asymmetry around the mean is called **skewness**:

$$\gamma_1 = \frac{\sigma_3}{\sigma^3} = \frac{\mathrm{E}((X - \mathrm{E}(X))^3)}{(\mathrm{E}(X^2) - (\mathrm{E}(X)^2)^{3/2}}.$$

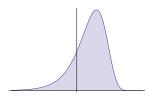


Skewness

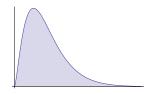
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Measure of asymmetry: for a unimodal density the coefficient γ_1 is negative if the left tail is longer and positive if the right tail is longer. It tells us to which side from the expected value is the bulk skewed:



$$\gamma_1 = -1.14$$



$$\gamma_1 = 1.26$$

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Kurtosis

The measure of "peakedness" is called (excess) kurtosis:

$$\gamma_2 = \frac{\sigma_4}{\sigma^4} - 3 = \frac{\mathrm{E}((X - \mathrm{E}(X))^4)}{(\mathrm{E}(X^2) - (\mathrm{E}(X)^2)^2)} - 3.$$

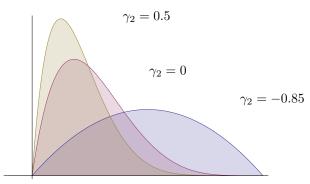


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This characteristics compares the shape ("peakedness") of the density with the normal distribution:



Quantiles

Important characteristics of random variables used especially in statistics are the **quantiles** and the **critical values**:

Definition

Let X be a random variable with distribution function F_X and let $\alpha \in (0,1)$. The point q_α is called the α -quantile of the variable X if

$$q_{\alpha} = \inf\{x | F_X(x) \ge \alpha\}.$$

Quantiles treated as a function of α are called the **quantile function** and are denoted as $F_X^{-1}(\alpha)$.

The $(1-\alpha)$ -quantile is called the α -critical value of the variable $X: c_{\alpha}=q_{1-\alpha}$.

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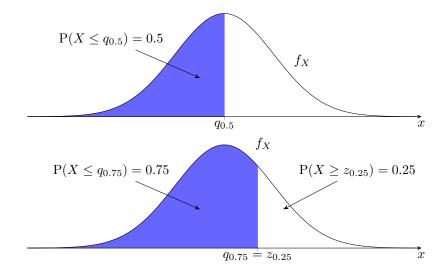
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The $(1-\alpha)$ -quantile is called the α -critical value of the variable $X: c_{\alpha}=q_{1-\alpha}$.

- For F_X strictly increasing and continuous, the quantile function $F_X^{-1}(\alpha)$ is the inverse of F_X in the classic sense.
- For some particular distributions, special notation is used, e.g., the quantiles of the Gaussian distribution are denoted as u_{α} and the critical values as z_{α} .

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Quantiles of the standard normal distribution





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Example – quantiles of the uniform distribution

Suppose that Romeo arrives at the meeting point according to the uniform distribution on the interval [0,1]. Find the 5% and 95% quantiles of his arrival.



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Suppose that Romeo arrives at the meeting point according to the uniform distribution on the interval [0,1]. Find the 5% and 95% quantiles of his arrival.

The distribution function is found by integrating the density. We are interested in the region, where the density is positive – the interval [0,1]:

$$F_X(x) = \int_{-\infty}^x f_X(t)dt = \int_0^x 1dt = [t]_0^x = x.$$



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The distribution function is monotone, thus we can easily find the quantile function as its inverse:

$$F_X(q_\alpha) = \alpha \quad \Rightarrow \quad q_\alpha = \alpha \quad \Rightarrow \quad F_X^{-1}(\alpha) = \alpha.$$

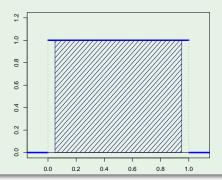
Therefore the quantiles are:

$$q_{0.05} = 0.05 = 3 \text{ min.}$$
 and $q_{0.95} = 0.95 = 57 \text{ min.}$

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Example – quantiles of the uniform distribution

With a 90% probability, Romeo arrives between the 3rd minute and the 57th minute.



Example – quantiles of a non-uniform distribution

Suppose that Juliet arrives at the meeting point according to the non-uniform distribution with the triangular density from above. Find the 5% and 95% quantiles of her arrival.

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Example - quantiles of a non-uniform distribution

Suppose that Juliet arrives at the meeting point according to the non-uniform distribution with the triangular density from above. Find the 5% and 95% quantiles of her arrival.

The distribution function is found by integrating the density. The observed interval has to be separated into two parts, because the function term is different.

For $y \in [0, 1/2]$:

$$F_Y(y) = \int_{-\infty}^y f_Y(t)dt = \int_0^y 4tdt = [2t^2]_0^y = 2y^2.$$

For $y \in [1/2, 1]$:

$$F_Y(y) = \int_0^{1/2} 4t dt + \int_{1/2}^y (4 - 4t) dt = 1/2 + \left[4t - 2t^2 \right]_{1/2}^y = 4y - 2y^2 - 1 = 1 - 2(y - 1)^2.$$

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Example – quantiles of a non-uniform distribution

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The quantile function is found as the inverse of the distribution function:

$$F_Y(q_{0.05}) = 0.05 \Leftrightarrow 2q_{0.05}^2 = 0.05 \Leftrightarrow q_{0.05} = \sqrt{0.05/2} \doteq 0.16 = 9.5 \text{ min.}$$

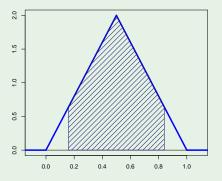
Similarly:

$$F_Y(q_{0.95}) = 0.95 \Leftrightarrow 1 - 2(q_{0.95} - 1)^2 = 0.95 \Leftrightarrow q_{0.95} = 1 - \sqrt{0.05/2} \doteq 0.84 = 50.5 \text{ min.}$$

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Example – quantiles of a non-uniform distribution

With a 90% probability, Juliet arrives between the 9.5th minute and the 50.5th minute.



The central interval denoting the time, between which the person arrives with a 90% probability, is considerably shorter for Juliet than for Romeo. This is in accordance with Juliet's arrival having a smaller variance.

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Important quantiles

Quantiles divide the population into groups according to probabilities. The important dividing points are called:

- $q_{0.5}$ median,
- $q_{0.25}$ lower quartile,
- $q_{0.75}$ upper quartile.

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This quantiles can give us an overview of the variable in question:

- The median provides a measure of location as an alternative to the expectation.
- The interquartile range $q_{0.75}-q_{0.25}$ provides a measure of dispersion as an alternative to the variance.

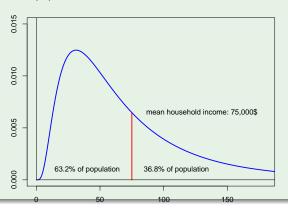
The expectation can sometimes differ from the median significantly. Especially for one-sided heavy-tailed distributions.



Expectation vs. median

Example – U.S. household incomes

According to the U.S Census Bureau, the mean yearly household income in 2014 was \$75,000. But 63.2% of population had lower incomes. The median income was \$56,000.



Definition

The moment generating function of a random variable X is a function $M(s)=M_X(s)$ defined as

$$M(s) = \mathcal{E}(e^{sX}).$$

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i.e., for a discrete or a continuous random variable X we have

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The generating function unambiguously determines the density f_X of the variable X (or the probabilities of its values). In fact the generating function is the Laplace transformation of the density. In particular, it allows us to easily compute the moments of the variable X.

Theorem

For a random variable X with a generating function M(s) it holds that:

$$E(X^n) = \frac{\mathrm{d}^n}{\mathrm{d}s^n} M(s) \big|_{s=0}.$$

Example - Poisson random variable

$$P(X = k) = \frac{\lambda^k e^{-\lambda}}{k!}, \ k = 0, 1, \dots$$



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We have:

$$\frac{d}{ds}e^{\lambda(e^s-1)} = \lambda e^s e^{\lambda(e^s-1)} \implies E(X) = \lambda,$$

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We have:

$$\frac{d}{ds}e^{\lambda(e^s-1)} = \lambda e^s e^{\lambda(e^s-1)} \implies \mathrm{E}(X) = \lambda,$$

$$\frac{d^2}{ds^2}e^{\lambda(e^s-1)} = ((\lambda e^s)^2 + \lambda e^s)e^{\lambda(e^s-1)} \implies \mathrm{E}(X^2) = \lambda + \lambda^2.$$

Thus
$$var(X) = (\lambda)^2 - (\lambda + \lambda^2) = \lambda$$
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Notice that M(s) is well defined only for $s \in [0, \lambda)$. For $s \ge \lambda$ the integral diverges.

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$$\frac{d}{ds}\frac{\lambda}{\lambda - s} = \frac{\lambda}{(\lambda - s)^2} \implies \mathrm{E}(X) = \frac{1}{\lambda},$$

$$\frac{d^2}{ds^2}\frac{\lambda}{\lambda-s} = \frac{2\lambda}{(\lambda-s)^3} \implies \mathrm{E}(X^2) = \frac{2}{\lambda^2} \quad \text{and} \quad \mathrm{var}(X) = \frac{1}{\lambda^2}.$$

Recap

The expectation of a random variable X gives us its center of mass or the expected average outcome.

 For discrete random variables it is the average of its possible values weighted by their probabilities:

$$EX = \sum_{k} x_k P(X = x_k).$$

 For continuous random variables it is the integral average of its possible values weighted by the density:

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$$E X = \int_{-\infty}^{\infty} x f_X(x) dx.$$

The ${\bf variance}$ of a random variable X gives us the expected quadratic distance of the random variable from its expectation. It is defined as

$$var X = E(X - EX)^2$$

and can be computed as:

$$\operatorname{var} X = \operatorname{E} X^2 - (\operatorname{E} X)^2.$$

