

# Basic notions of probability

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## Probability and Statistics

BIE-PST, WS 2026/27, Lecture 1



# Requirements for passing the course

- **Tutorials:**

- ▶ there will be 6 small tests, each for 5 points, the 5 best results will count – 25p
- ▶ homework assignment – 15p (report + presentation)
- ▶ needed at least 20p from 40p possible.

- **Exam:**

- ▶ compulsory written exam max 60p – at least 30p needed
- ▶ points from exam and tutorials will be added
- ▶ optional theoretical exam – max 5p
- ▶ taking the theoretical exam is possible only after successfully passing the written exam.

# Bibliography

## English books:

- D. P. Bertsekas & J. N. Tsitsiklis: **Introduction to Probability**, Athena Scientific MIT (2008)
- G. R. Grimmett & D. R. Stirzaker: **Probability and Random Processes**, Oxford University Press (2001)
- Ch. M. Grinstead & J. L. Snell: **Introduction to Probability**, AMS (1997) – (online)

# Content

- **Probability theory:**

- ▶ **Events, probability**, conditional probability, Bayes' Theorem, independence of events.
- ▶ Random variables, distribution function, functions of random variables, characteristics of random variables: expected value, variance, moments, generating function, quantiles, critical values, important discrete and continuous distributions.
- ▶ Random vectors, joint and marginal distributions, independence of random variables, conditional distribution, functions of random vectors, covariance and correlation.
- ▶ Markov's and Chebyshev's inequality, weak law of large numbers, strong law of large numbers, Central limit theorem.

- **Mathematical statistics:**

- ▶ Point estimators, sample mean, sample variance, properties of point estimators, Maximum likelihood method.
- ▶ Interval estimators, hypothesis testing, one-sided vs. two-sided alternatives, linear regression, estimators of regression parameters, testing of linear model.

# Probability and statistics

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What do we understand as *random*? In real life we often encounter processes (experiments, tests, natural phenomena, . . .), for which **we are not sure**, how they will end and which result will occur.

Exact prediction may not be possible because they are either too complex or we do not have all necessary information available.

Usually we say that the result is unpredictable or **random** and is given by **chance**.

# Probability theory vs mathematical statistics

**Probability theory** quantifies the unpredictability from a mathematical point of view.

- Outcomes of an experiment are assigned **probability**, giving the ideal proportion of cases when the outcome will occur.
- Starting from simple models, complex problems may be solved.
- E.g., if we know that a coin is balanced, we can compute what is the probability of getting  $100 \times$  Heads out of 1000 tosses.

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- Starting from simple models, complex problems may be solved.
- E.g., if we know that a coin is balanced, we can compute what is the probability of getting  $100 \times$  Heads out of 1000 tosses.

**Mathematical statistics** estimates the unpredictability using experimental data.

- Outcomes of a repeated experiment are used for estimation.
- Probabilistic models are suggested and verified.
- E.g., if we get only  $100 \times$  Heads out of 1000 tosses, is it enough evidence to say that a coin is not balanced?

# Classical definition of probability

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## Imperfection of the definition:

- What to do if the die is unbalanced?
- What to do if there are infinitely many possible results?

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✓ Recall yourself the basic combinatorics!

# Recap of Combinatorics

Consider a set of  $n$  elements, where  $n \in \mathbb{N}$ .

- The number of ways to order these elements (**permutations**) is  $n!$
- The number of ways to select  $k$  elements without repetitions when the order is important (**variations**) is  $\frac{n!}{(n-k)!}$ .
- The number of ways to select  $k$  elements with repetitions when the order is important (**variations with repetition**) is  $n^k$ .
- The number of ways to select  $k$  elements without repetitions when the order is not important (**combinations**) is  $\binom{n}{k}$ .
- The number of ways to select  $k$  elements with repetitions when the order is not important (**combinantions with repetition**) is  $\binom{n+k-1}{k}$ .

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## Imperfection of the definition:

- How to introduce unequal distribution of probability?
- What to do with objects of infinite size?

# Geometric definition of probability

## Example – Romeo and Juliet

Romeo and Juliet have to meet at a secret place between midnight and 1 a.m. Each of them arrives at a random moment between midnight and 1 a.m., but will wait for only 15 minutes. If the partner does not arrive, the waiting person will leave.

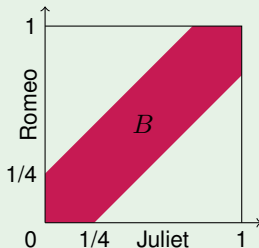
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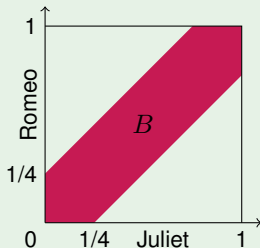


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The total area is 1. The coloured area corresponds to the successful meeting.

$$P(B) = \frac{1 - (3/4) \cdot (3/4)}{1} = \frac{7}{16}.$$

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An arbitrary possible result  $\omega \in \Omega$  is called an **outcome** (elementary event).

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The Sample space should be detailed enough to distinguish between different results but it should ignore unimportant details.

# Possible sample spaces

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- Height of the missile above the earth surface:  $\Omega = [0, +\infty)$
- Random text in email in UTF-32 encoding (constant length) of maximal length 1MB.  
The maximal number of characters in the message is

$$\frac{1 \text{ MB}}{32 \text{ bits}} = \frac{2^{20} \text{ bytes}}{4 \text{ bytes}} = 2^{18} = 262144.$$

Thus:  $\Omega = \{(x_1, x_2, \dots, x_{2^{18}}) \mid x_i \in \mathbb{N}, 0 \leq x_i < 2^{32}, \text{ for all } i\}$

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- Series of  $n$  rolls with one die, where we are interested only in numbers of appearance of each side:

$$\Omega = \left\{ (k_1, k_2, k_3, k_4, k_5, k_6) \in \mathbb{Z}_+^6 : \sum_{l=1}^6 k_l = n \right\}.$$

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- Throwing darts into  $T \subset \mathbb{R}^2$ :  $\Omega = T \cup \{*\}$ , where  $\{*\}$  is a one point set representing the outcome “the dart does not reach the target”.

If the target is divided into, say, 5 strips and we are interested only in which strip was reached:  $\Omega = \{1, 2, 3, 4, 5, *\}$ .

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- Tossing a coin until first Head appears: countable space  $\Omega = \{\omega_1, \omega_2, \omega_3, \dots\}$ , where  $\omega_i$  means that the first  $i - 1$  tosses are Heads and the  $i$ -th toss is Tail.

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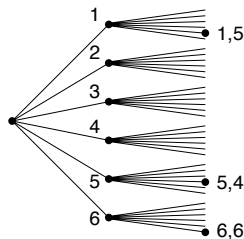
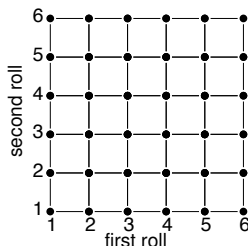
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- Tossing a coin infinitely many times: countable space  $\Omega = \{H, T\}^{\mathbb{N}}$ .

# Visualization of an outcome of a series of experiments

Two rolls of a die:

A **coordinate** description or a sketch in the form of a **tree** where each sequence of results of particular rolls corresponds to a single leaf that is uniquely determined by the path from the root to the leaf (in the illustration, only 3 leaves corresponding to 3 outcomes are explicitly marked).



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## Example – Rolling a die (6-sided)

*Express the event “an even number appears” as a set.*

Even numbers are 2, 4, and 6. The event  $A$  denoting that “an even number appears” is

$$A = \{2, 4, 6\} \subset \Omega.$$

# Operations with events

It is possible to apply all classical set operations on events (events are sets).

In probability theory, a specific terminology is used for this operations:

- $A^c$  complement of  $A$  – **no outcome in  $A$  occurs**
- $A \cap B$  intersection of  $A$  and  $B$  – **both  $A$  and  $B$  occur**
- $A \cup B$  union  $A$  and  $B$  – **either  $A$  or  $B$  or both**
- $A \setminus B$  difference  $A$  and  $B$  –  **$A$  but not  $B$**
- $A \subset B$  subset – **if  $A$  then  $B$**
- $\emptyset$  empty set – **impossible event**
- $\Omega$  collection of objects – **whole sample space**
- $\omega$  member of  $\Omega$  – **outcome, elementary event**

# Structure of events

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Clearly:  $\Omega \in \mathcal{F}$  – contains the sample space itself.

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## Examples – possible $\sigma$ -algebras

- $\mathcal{F} = \{\emptyset, \Omega\}$  is a  $\sigma$ -algebra.
- For an arbitrary  $A \subset \Omega$ ,  $\mathcal{F} = \{\emptyset, A, A^c, \Omega\}$  is a  $\sigma$ -algebra.
- $\mathcal{F} = 2^\Omega$  – all subsets create a  $\sigma$ -algebra;
- Borel  $\sigma$ -algebra on  $\mathbb{R}$  – smallest  $\sigma$  algebra containing all open intervals.

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A **probability measure**  $P$  on  $(\Omega, \mathcal{F})$  is a function  $P : \mathcal{F} \rightarrow \mathbb{R}$  satisfying:

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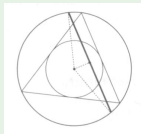
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The choice of  $P$  determines what we understand as “**random**”. Vague assignment can lead to “paradoxes”.

# Bertrand paradox

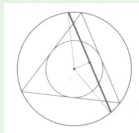
## Example – Bertrand paradox (Joseph Bertrand, 1889)



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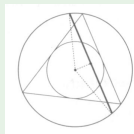


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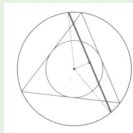
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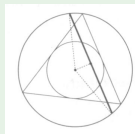
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# Intermezzo

## How to establish $\mathcal{F}$ ?

- Finite or countable  $\Omega$ :
  - ▶ We can take  $\mathcal{F}$  as all subsets of  $\Omega$ . ( $\mathcal{F} = 2^\Omega$ , i.e., power set of  $\Omega$ )
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  - ▶ Events are arbitrary subsets of  $\Omega$ .
- For an uncountable  $\Omega$ :
  - ▶ It is not possible to assign a positive probability to each  $A \subset \Omega$ , because then we would have  $P(\Omega) = \infty$ .
  - ▶ If  $\Omega \subset \mathbb{R}^d$  is some subinterval of  $\mathbb{R}^d$  (e.g.,  $[0, +\infty)$ ) we can take  $\mathcal{F}$  as the Borel  $\sigma$ -algebra on  $\Omega$ .
  - ▶ Except for an at most a countable subset, each singular point must have a zero probability.

# Definition of probability for “classical” settings

## Definition of probability for uniform distribution of finite number of outcomes:

If  $\Omega$  is finite with equally likely realizations:

$$P(A) = \frac{\#A}{\#\Omega} = \frac{\text{number of favorable outcomes}}{\text{number of all outcomes}}.$$

## Geometric definition of probability:

Let  $\Omega$  be any arbitrary space with a measure  $\mu$ , i.e., we can measure size (area, capacity, etc.), and  $0 < \mu(\Omega) < +\infty$ . For any event  $A \subset \Omega$  we define:

$$P(A) = \frac{\mu(A)}{\mu(\Omega)} = \frac{\text{size of } A}{\text{size of } \Omega}.$$

It can be easily verified that both approaches satisfy the formal definition of probability as stated above.

# Properties of probability

## Theorem

*Let  $A$  and  $B$  be events on a probability space with measure  $P$ . Then it holds that:*

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## Consequences:

- $0 \leq P(A) \leq 1$  – from v)
- $P(A \cup B) \leq P(A) + P(B)$  – from iv)

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- i) We create a sequence of disjoint events:  $A_i = \emptyset$  for all  $i \in \mathbb{N}$ . From property **iii) of probability measure** we have

$$P(\emptyset) = P\left(\bigcup_{i=1}^{+\infty} \emptyset\right) = \sum_{i=1}^{+\infty} P(\emptyset),$$

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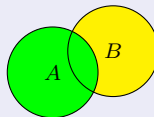
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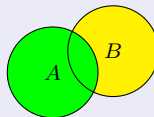
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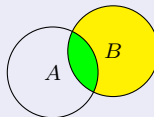
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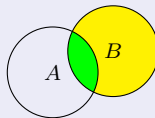
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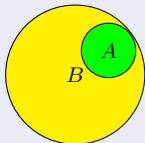
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For 3 events:

$$P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) - P(B \cap C) + P(A \cap B \cap C)$$

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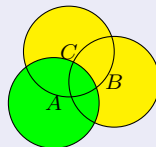
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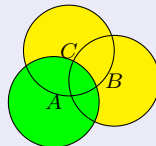
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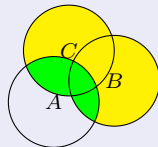
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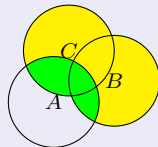
From point **ii)** of the previous theorem it follows that

$$P(A \cup B \cup C) = P(A) + P((B \cup C) \setminus A).$$

Since  $P(B \cup C) = P((B \cup C) \setminus A) + P(A \cap (B \cup C))$ , we have:

$$P(A \cup B \cup C) = P(A) + P(B \cup C) - P((A \cap B) \cup (A \cap C)).$$

and again, applying point **ii)** of the previous theorem to  $P(B \cup C)$  and to  $P((A \cap B) \cup (A \cap C))$



# Properties of probability

## Proof

- i) The set  $\bigcup_{i=1}^{+\infty} A_i$  can be written as a disjoint union  $\bigcup_{i=1}^{+\infty} \left( A_i \setminus \bigcup_{k=1}^{i-1} A_k \right)$ . From property **iii)** of probability measure we have

$$P\left(\bigcup_{i=1}^{+\infty} A_i\right) = P\left(\bigcup_{i=1}^{+\infty} \left(A_i \setminus \bigcup_{k=1}^{i-1} A_k\right)\right) = \sum_{i=1}^{+\infty} P\left(A_i \setminus \bigcup_{k=1}^{i-1} A_k\right) \leq \sum_{i=1}^{+\infty} P(A_i).$$

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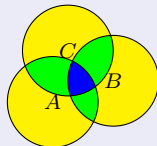
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finally we have:

$$P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(A \cap C) - P(B \cap C) + P(A \cap B \cap C).$$



# Continuity of probability

## Theorem

Let  $A_1, A_2, \dots$  be a sequence of events **increasing** in the sense of inclusion, i.e., such that  $A_1 \subset A_2 \subset A_3 \subset \dots$ . If we denote

$$A = \bigcup_{i=1}^{+\infty} A_i,$$

then  $P(A) = \lim_{n \rightarrow +\infty} P(A_n)$ .

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Similarly, let  $B_1, B_2, \dots$  be a sequence of events **decreasing** in the sense of inclusion, i.e., such that  $B_1 \supset B_2 \supset B_3 \supset \dots$ . If we denote

$$B = \bigcap_{i=1}^{+\infty} B_i,$$

then  $P(B) = \lim_{n \rightarrow +\infty} P(B_n)$ .

# Continuity of probability

## Proof

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The set  $A$  can be written as the disjoint union  $A = \bigcup_{i=1}^{+\infty} (A_i \setminus A_{i-1})$



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We prove the second part of the statement by means of the De Morgan rules and the proof of the first part:

$$P(B) = P\left(\bigcap_{i=1}^{+\infty} B_i\right) = P\left(\left(\bigcup_{i=1}^{+\infty} B_i^c\right)^c\right) = 1 - P\left(\bigcup_{i=1}^{+\infty} B_i^c\right)$$



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The sets  $B_i^c$  satisfy the assumptions of the first part of the Theorem and thus:

$$P(B) = 1 - \lim_{n \rightarrow \infty} P(B_n^c) = \lim_{n \rightarrow \infty} (1 - P(B_n^c)) = \lim_{n \rightarrow \infty} P(B_n).$$



# Recap

A random experiment is represented using a probability space  $(\Omega, \mathcal{F}, P)$ , where

- $\Omega$  is the set of possible results;
- $\mathcal{F}$  is a system of subsets of  $\Omega$ ;
- elements  $A \in \mathcal{F}$  are called random events;
- the probability measure  $P$  is a function which assigns to the random events a real value from 0 to 1, representing the ideal proportion of cases in which the events occur.

If there is only a finite number of possible results with equal probabilities, then

$$P(A) = \frac{|A|}{|\Omega|}.$$